BEHAVE: Behavior-Aware, Intelligent and Fair Resource Management for Heterogeneous Edge-IoT Systems

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Abstract—Edge computing is an emerging solution to support the future Internet of Things (IoT) applications that are delay-sensitive, processing-intensive or that require closer intelligence. Machine intelligence and data-driven approaches are envisioned to build future Edge-IoT systems that satisfy IoT devices’ demands for edge resources. However, significant challenges and technical barriers exist which complicate the resource management for such Edge-IoT systems. IoT devices running various applications can demonstrate a wide range of behaviors in the devices’ resource demand that are extremely difficult to manage. In addition, the management of multidimensional resources fairly and efficiently by the edge in such a setting is a challenging task. In this paper, we develop a novel data-driven resource management framework named BEHAVE that intelligently and fairly allocates edge resources to heterogeneous IoT devices with consideration of their behavior of resource demand (BRD). BEHAVE aims to holistically address the management technical barriers by: 1) building an efficient scheme for modeling and assessment of the BRD of IoT devices based on their resource requests and resource usage; 2) expanding a new Rational, Fair, and Truthful Resource Allocation (RFTA) model that binds the devices’ BRD and resource allocation to achieve fair allocation and encourage truthfulness in resource demand; and 3) developing an enhanced deep reinforcement learning (EDRL) scheme to achieve the RFTA goals. The evaluation results demonstrate BEHAVE’s capability to analyze the IoT devices’ BRD and adjust its resource management policy accordingly.

Index Terms—Edge computing; Internet of Things; BRD modeling; Resource management; Heterogeneous IoT devices; Deep reinforcement learning.

1 INTRODUCTION

Growing Internet of Things (IoT) applications raise the demand for edge computing for data processing and application intelligence. Integrating machine intelligence, IoT, and edge computing [1] benefits various applications such as virtual reality, health informatics, secure cyberspace, and urban infrastructure. It is a promising vision to build a future “Edge-IoT” environment converged with machine intelligence and data-driven approaches. Edge-IoT systems can support a massive number of diverse smart devices [2] with heterogeneous applications that can be delay-sensitive or require closer intelligence. To enable such vision, there are some significant challenges to overcome. On the one hand, a massive number of IoT devices can run applications with various resource demands and different priorities. These devices may demonstrate a wide range of possible “behavior” in resource demand, and exhibit abnormal or abusive behavior due to potential software/hardware malfunction or IoT network attacks [3], [4]. Since there is a tremendous device variety and complex behavior patterns of resource demand, more advanced methods are needed to analyze these patterns. On the other hand, the edge servers are expected to dynamically provide multidimensional resources (CPU, memory, and bandwidth) at geospatially distributed points and different levels of network hierarchy in a fair and efficient fashion. These challenges together severely complicate the required edge resource management and scheduling algorithms. Most of the current resource allocation research either focuses on a specific application, or optimizes specific operations such as mobile offloading, migration, and orchestration [5], [6] from energy efficiency and utilization perspective. The existing edge computing schemes neither consider resource allocation with influence of behavior of resource demand (BRD) of IoT devices, nor account for fairness in resource allocation.

In this paper, we develop a novel data-driven resource allocation framework named BEHAVE that intelligently and fairly allocates resources to heterogeneous IoT devices with consideration of their complex BRD. To holistically address the above technical challenges, and align with BEHAVE goals, we develop the following:

- A novel scheme to efficiently model and assess various BRD for heterogeneous IoT devices based on their resource requests and usage. The modeling approach profiles devices’ BRD in two granularities: single resource request and temporal multiple requests over certain period of time. High-quality behavior features are extracted from large-dimensional behavior data using a novel deep learning technique. The outputs of the BRD models are leveraged
to generate BRD Index for each device (BRDI) that assesses the normality of its BRD. BRDI is exploited later for resource allocation.

- A new Rational, Fair, and Truthful Resource Allocation (RFTA) model to allocate the available multi-type edge resources (memory, CPU, and bandwidth) efficiently with consideration of dynamic IoT devices’ BRD. The model aims to optimize the IoT devices’ gain with consideration of their BRD and achieve fairness in the resources allocated to IoT devices that have different BRDI values; it also support the IoT devices’ truthfulness while reporting their resource demands.

- An enhanced deep reinforcement learning (EDRL) scheme for edge resource allocation to achieve the goals of the RFTA model by formulating a novel Markov decision process (MDP) and efficiently overcomes the “dimensionality” problem in reinforcement learning through accurate approximation of the value function.

The rest of the paper is organized as follows. The related work is presented in Section 2. Section 3 describes the motivation of BEHAVE, its system architecture, and the design merits of its components. The scheme for assessment of IoT devices’ BRD is presented in Section 4. Section 5 presents the RFTA resource allocation model. The EDRL based resource allocation scheme is illustrated in Section 6. Section 7 presents the performance evaluation and the paper concludes in Section 8.

2 RELATED WORK

Resource allocation in the context of edge computing has recently been one of the emerging topics in edge computing research [7], [8], [9], [10]. Some resource allocation proposals aim to optimize performance objectives such as power efficiency, delay, and computation rate [11], [12], [13]. The work in [14] tackled the problem of admission control and resource allocation with optimization of the devices’ utility using Lyapunov dynamic stochastic optimization approach. The authors in [7] studied the problem of joint task offloading and resource allocation to maximize the users’ tasks offloading gains. The work in [9] investigated how to allocate edge resources for average service response time minimization. Machine learning including reinforcement learning (RL) [15] techniques has also been adopted for edge resource management [16], [17]. The work in [18] exploited DRL to manage the resources at the network edge. The authors in [16] leveraged DRL to construct an intelligent offloading system for vehicular edge computing. In [17], the authors designed an intelligent agent at the edge computing node to create a real-time adaptive policy for computational resource allocation of multiple users in order to improve the average end to end reliability. The deep Q-network (DQN) approach proposed in [19] is a model-free approach to efficiently manage resources at the network edge through tasks offloading and control the resource allocation among the edge servers. The DRLRA approach proposed in [20] is a smart, DRL based resource allocation scheme, which allocates computing and network resources adaptively to minimize IoT devices’ service time. Both approaches do not account for integrating edge resource availability from several edge servers and resource demands from heterogeneous devices with various BRD and priorities.

Given the related work for edge computing resource allocation, none of the existing work tackles the resource allocation problem with consideration of IoT devices’ BRD in allocation decision-making as they only targeted optimization of certain performance metrics. IoT devices’ behavior analysis has been widely studied in both academia and industry, which typically involves applying various machine learning techniques to analyze data traffic and achieve IoT device behavior modeling. Behavior modeling collects, processes, profiles, and models the patterns of behavior data. Specific behavior modeling methods were applied to various IoT management tasks, including device identification [21] and intrusion detection [22], and access control [23]. Most of the existing work on the analysis of IoT devices’ behavior are inadequate to model the complex behavior of heterogeneous IoT devices from the resource demand perspective. Moreover, the BRD of heterogeneous IoT devices needs to be profiled by considering edge computing service information such as resource usage, resource request duration, and resource request density. The modeling method should be able to measure the BRD data in various formats, length, and temporal relationship (e.g., time series and non-time series data).

3 MOTIVATION, ARCHITECTURE AND DESIGN MERITS OF BEHAVE

In this section, we present the motivation for associating the BRD of IoT devices with edge resource allocation. Moreover, we describe the architecture of BEHAVE and the merits of the design of its components.

3.1 Motivation of BEHAVE

In the Edge-IoT systems, there are heterogeneous IoT devices with various demands for edge resources to process their tasks. Some typical examples are shown in Fig 1. On the one hand, considering the significant impact of the irregular BRD of certain devices over the limited edge resources, it is necessary for the edge resource management framework to associate the resource allocation decisions with the devices’ BRD, such that the devices with normal BRD are rewarded and the ones with irregular BRD are restricted from resource access. Without BRD monitoring, the edge computing service will be subjected to resource abuse and scheduling disorders. For example, compromised IoT devices such as botnet may launch DDoS attacks on the edge servers by flooding malicious requests to their service APIs. Malfunctioned IoT devices can also exhibit irregular BRD due to random glitches in their resource demand. On the
other hand, the edge resources are limited and are expected to be dynamically allocated at distributed points and different levels of network hierarchy. Edge resources are distributed over multiple edge servers which may have different resources utilization levels. This severely complicates the resource allocation and scheduling algorithms. Therefore, it is important to develop resource allocation systems such that IoT devices acquire resources based on their BRD and edge resources are utilized in the most efficient manner. Resource allocation in such context must not only be tied to performance metrics but also support rationality through achieving certain gain for the IoT devices that exhibit normal BRD. In addition, being fair in resource allocation among devices with variable BRD and encouraging these devices to be truthful in resource demand are essential requirements such that the limited resources of the edge are not wasted.

In BEHAVE, we associate the edge resource allocation with the BRD of IoT devices. For example, devices that request large amount of resources for applications’ tasks processing without justification as their applications do not require having these resources, will be restricted. However, restriction by simply blocking these devices may not be the best practice as not all the devices exhibit the same level of irregular BRD. Some of them may have irregular BRD temporarily as they suffer an instant glitch in their operation. Therefore, we adopt the idea of continuous monitoring the devices BRD and control the edge resource allocation accordingly. The Edge-IoT system considered in this paper comprises IoT devices with heterogeneous behaviors, different resource demands and various priorities. The rate at which IoT devices request resources and the resource capacity at the edge change in a dynamic fashion at different time slots. Thus, DRL [24] is exploited in BEHAVE to generate resource allocation actions as it is capable of modeling complex problems such as resource allocation in Edge-IoT. Moreover, DRL does not require any prior knowledge about the Edge-IoT system model to learn certain resource allocation policy. DRL suits such resource allocation problem where the system is dynamic and long term reward is sought.

### 3.2 Architecture of BEHAVE

BEHAVE architecture is presented in Fig. 2. The key components include BEHAVE controller, the RFTA Model, the IoT devices, and the edge servers. These components coordinate with each other to achieve the ultimate resource allocation that maximizes the gain of IoT devices according to their exhibited BRD. The IoT devices initiate resource requests. The edge servers provide CPU, memory and bandwidth resources. Both the IoT devices and the edge servers share their state information with the managers located at the controller. For example, the IoT devices send their resource requests and the edge servers provide information about the available resources, resources usage logs and servers’ capacity. The management core of BEHAVE consists of the controller and the RFTA model which are located at the edge. The controller includes the BRD manager and the EDRL manager. The BRD manager collects devices’ BRD data. Then, it creates profiles for the devices BRD, models their BRD patterns based on the built profiles, and assesses the devices’ real-time BRD. We develop a novel technique that collects devices’ BRD data and characterizes the interactions between the edge servers and the IoT devices. The BRD pattern of each device in the normal operation status is modeled to identify devices with irregular BRD. The identification task is formulated as an unsupervised one-class classification (OCC) problem to detect the outliers of the BRD baseline without any labeling overhead. The EDRL manager receives the state information from the edge servers and the devices’ BRD information, and formulates its MDP. Then, it runs EDRL to generate the edge resource allocation policy that aligns with the RFTA model optimization objectives and constraints. The RFTA model aims to maximize the IoT devices’ gain with efficient resource utilization under certain BRD related constraints.

### 3.3 Design Merits of BEHAVE

In this subsection, we present the design merits of the main components presented in BEHAVE architecture including BRD management, RFTA model, and EDRL resource management. For BRD profiling, we define two granularities to profile the BRD of devices from short-term and long-term views: 1) single resource request granularity and 2) temporal requests granularity. These granularities align with the following operation characteristics of IoT devices: 1) heterogeneous devices offload various IoT applications’ tasks with different resource consumption and frequency density which makes their BRD connected to different time scales; 2) many IoT devices have on-demand activity patterns changing with time because of the interaction with users. For example, smart camera installed at the entrance of a building and
executes a face detection application. This application has variable resource demand as the number of people entering the building is unsteady over the time. For BRD modeling, we propose a novel Generative Adversarial Network (GAN)-based Encoder-Decoder (GAN-ED) deep learning framework to generate compact feature representation from large-dimension sequences. The proposed GAN-ED has the following key advantages: 1) smaller BRD dataset where the generator ability of GAN provides oversampled new samples during the training process; 2) advanced feature representation ability benefiting from the adversarial network. Thus, GAN-ED outperforms the traditional exploratory analysis measurements and statistical models [26] which are not feasible to capture the data dependency in the time series [27] and experience difficulties to determine the model parameters. It is also better than the widely adopted auto-encoder [28], which is constrained by requiring a large number of data samples and lacking model ability for long-term sequence to find the time-dependent BRD pattern. For BRD assessment, we introduce an unsupervised one-class neural network (OCNN)-based [29] irregular BRD assessment approach, which is concatenated with the previous deep learning structure to craft an efficient end-to-end model and reduce the requirement of costly class labeling in OCC.

We propose RFTA model for resource allocation such that each device receives the resource allotment that is consistent with its BRD while maintaining efficient resource utilization. RFTA is distinguished from the existing resource allocation models because: 1) the IoT devices are assumed to have heterogeneous BRD and they have budget to obtain resources that is determined according to their exhibited BRD. 2) The resource allocation problem is formulated as a multi-resource allocation problem as the type of resources is taken into consideration and the setting of the system model incorporates multiple edge servers with multiple resource types. 3) The allocation problem is casted as behavior oriented allocation with the goal of maximizing devices’ gain constrained by their budgets. 4) the proposed model also has the following unique characteristics: i) Rationality, as each IoT device achieves certain gain ≥ 0 that is optimized to boost the IoT system performance; ii) Fairness, as the model aims to allocate resources fairly to IoT devices with distinct BRD and variable budgets; iii) Truthfulness, since the resource requests initiated by the IoT devices should be truthful in order to maximize their gain.

The proposed EDRL scheme has three unique merits. 1) It targets optimization of the IoT system performance with consideration of devices’ BRD and devices’ budgets. 2) It develops a novel MDP that features a composite state. This state comprises IoT device related state information such as resource demand, budget, application priority, and state of multiple edge servers including their resource capacity and utilization. Thus, our EDRL differs from the DRL used in the current other work which focuses on allocation from one centralized edge server. 3) It incorporates a unique mapping function between the composite state elements, which enhances the accuracy of the value function approximation and consequently, the resource allocation action quality.

4 Modeling and Assessment of BRD for IoT Devices

This section presents the scheme functionality to achieve modeling and assessment of IoT devices’ BRD.

4.1 Modeling of IoT Device BRD

The modeling process of each device BRD (presented in Fig. 3) starts with data collection in which data is collected on the edge server by logging the resource usage and the workload traffic in the normal status of the device for every resource request. Then, profiling of BRD in the two granularities engages as follows,

![Fig. 3. Modeling of devices’ BRD](diagram)

1. Single Request (SR) Granularity: The single request granularity focuses on the device’s BRD during one request received and processed by the edge servers. The BRD is profiled with multiple attributes that measure resource usage and workload traffic. The modeling in this granularity aims to identify irregular BRD in each request. The BRD profiles in this granularity include request duration, request workload size, request CPU/Mem/Disk IO usage and occupancy time, count of network connections, transport-layer protocol (e.g., TCP/UDP), and application-layer protocol (e.g., HTTPS/HTTP/MQTT/COAP).

2. Temporal Requests (TR) Granularity: Considering the fact that many IoT devices have on-demand activity pattern caused by the interaction between the applications and the users, the BRD of devices should also be profiled in a long-term view. Even if the current requests are identified as normal, there may exist irregular requests over a certain period of time. For example, a smart camera is not expected to send requests in a high frequency when the crowd density is low at night. Therefore, we propose the temporal requests granularity to profile the time-related requests. This granularity consists of three BRD profiles: the number of requests, total workload size, and resource occupancy time. The BRD data is sampled in the whole day at a fixed interval (e.g., 10 minutes). Thus, a time series is formed with a sequence of data points, where each data point is a vector of the three attributes.
Given the BRD profiles in TR granularity, we extract the high-quality features of BRD using GAN-ED. It is inspired by BiGAN [30], which offers the theoretical design of projecting real data into the feature space of its generative network. GAN-ED consists of an encoder network (E), a generative network (G) acting as the decoder, and a discriminator network (D). In GAN-ED, we utilize an encoder (E) as the feature extractor that compresses a long data series into a short fixed feature vector. The decoder G learns to map samples from an arbitrary latent distribution to the real time series distribution. The discriminator D distinguishes between the real and generated time series. In this way, D advances the learning ability of both E and G by guiding them to learn the true data distribution from the original inputs. Moreover, we adopt LSTM [31] neurons in the hidden layers of both E and G to learn the time dependencies between data points. The left part of Fig. 4 shows the model architecture and the data flow between the network components. Specifically, the input of E is the raw time-series profiles \( x \) and its output is the compressed data representation \( z' = E(x) \) in the feature space. The input of G comprises a sequence of noise points \( z \) with the same length as the feature vector and its output is the generated time series \( x' = G(z) \). The input of D consists of \( x \) and the output \( z' \) and \( x' \) from \( E \) and \( G \) respectively, while the output of D is the discrimination results (either valid or fake). In the model training phase, D discriminates jointly original data and feature space \((x, E(x))\) versus \((G(z), z)\), where the optimization goal of D is to maximize the probability of identifying \((x, E(x))\) as valid and \((G(z), z)\) as fake. On the other hand, E and G are jointly trained to minimize the identification probability of \((G(z), z)\). Once the training completes, the optimal E and G invert each other to deceive D. Therefore, the above training process is defined as a minimax game imposed among the three sub-networks that alternatively improve in every iteration. Let the length of input \( x \) be \( n \), and the similarity estimator be \( E_t \). The optimization function is formulated as:

\[
\min_{E,G,D} \max_{E_t} E_t [\log(D(x, E(x)))] + E_t [\log(1 - D(G(z), z)]
\]

(1)

Since \( n \) is not fixed considering the variety of IoT devices and applications, the number of features is experimentally determined.

4.2 Assessment of BRD

In this subsection, we explain the BRD assessment process (presented in Fig. 5) through detection of irregular BRD using the BRD datasets and the extracted features. Furthermore, we design a longitudinal measurement

![Fig. 5. The scheme of devices’ BRD assessment](image)

for the real-time BRD of the device that uses historical detection results to generate its BRDI. We formulate the detection task as an OCC problem, where the one class is the baseline for detection, and any outlier activity that is distinct from baseline is treated as an irregular BRD. Specifically, we construct individual detectors for the SR and TR datasets, and then measure the likelihood (in value range \([0, 1]\)) of a new BRD instance following the baseline. The OCNN model is adopted for detection of the irregular BRD rather than the commonly used One-class Support Vector Machine (OC-SVM) [32], because of the following unique advantages: 1) it learns the distribution of the BRD data with extra hidden neural networks where the decision boundary between normal and abnormal is highly nonlinear; 2) it models multi-dimensional features efficiently without using the computation-intensive kernel functions; and 3) it fits the previously trained Encoder network to build an end-to-end detector for the TR dataset. The OCNN model consists of one input layer, one hidden layer, and one output layer. For the SR dataset, OCNN input is the raw BRD data. For the TR dataset, however, the input layer is connected to the output layer of the encoder network, and the input is the value of the extracted features. The hidden layer is used to classify the input values according to the OCC objective. The output layer has sigmoid activation that calculate the probability of the BRD to be deemed as the degree of “normality” in range \([0, 1]\), rather than a binary normal or abnormal classification. Let the inputs be \( X \) with \( N \) features, the weights of the output layer and the hidden layer be \( w \) and \( V \) respectively, the threshold of irregular percentage in the training dataset be \( \nu \), and the decision boundary bias for normal BRD be \( r \). The optimization function of the training in OCNN model is formulated as:

\[
\min_{w,v,r} \frac{1}{2} (\|w\|^2 + \|V\|^2) + \frac{1}{N} \sum_{i=1}^{N} \max(0, r - (w, g(V.X_i))) - r
\]

(2)

where \( \nu \) is set according to the noise percentage of the training dataset. The right part of Fig. 4 presents the integration between the encoder network in GAN-ED and the OCNN detector.
To generate the devices’ BRDI, the devices are monitored and the detection of the irregular BRD is performed periodically. The BRDI is calculated jointly in the two granularities as follows, First, the detection results in the SR granularity are recorded with time stamps. Its BRDI ($\Gamma_{SR}$) is dynamically updated with the series of historical detection results. We assess the influence of each result according to the difference between its time and the current time. To determine the time impact, we employ Newton’s Law of Cooling function \([33]: \Gamma_{SR} = \sum_{t=1}^{T} P_t \cdot e^{-\alpha t}\), where \(T\) is the number of historical records, \(\{P_1, P_2, ..., P_T\}\) are the corresponding BRD diagnosis records ordered from the most recent to the least recent, and \(\alpha\) is the contribution parameter controlling how fast \(P_i\) degrades. Second, the TR BRDI ($\Gamma_{TR}$) is updated based on the detection result of GAN-ED+OCNN that is performed once per day. Note that both \(\Gamma_{SR}\) and \(\Gamma_{TR}\) have the value in range \([0, 1]\) indicating the BRD regularity degree. Finally, the total BRDI is jointly calculated as:

$$\Gamma = \beta_1 \cdot \Gamma_{SR} + \beta_2 \cdot \Gamma_{TR} \tag{3}$$

where weights \(\beta_1 + \beta_2 = 1\) and \(\Gamma \in [0, 1]\). The setting of \(\beta_1\) and \(\beta_2\) is determined according to the device type. If the device has no or only minor BRD change in TR granularity, \(\beta_2\) could be close to 0. If TR BRD pattern has obvious change along the timeline, \(\beta_2\) is given more weight. \(\Gamma\) is proportional to the normality of the device BRD. BEHAVE takes the BRDI of devices as a factor to define the devices’ budgets in the subsequent resource allocation model.

5.1 System Model and Budget Determination

In this subsection, we describe the system model and define a budget determination function for each device. The system model consists of multiple edge servers that have resources with certain capacity and different types including CPU, memory and bandwidth. In addition, the model incorporates a group of heterogeneous IoT devices that need to acquire resources to process their tasks. The communication resources are assumed to be available for the initial data transfer between the devices and the edge. As the number of devices increases, the demand for resources will increase and the complexity and overhead will escalate. Our system aims to balance the tradeoff between performance and complexity. Thus, it assumes that the network is divided into multiple edge domains. Each edge domain consists of one controller, multiple servers and specific number of IoT devices. The number of IoT devices is matched with the network capacity. For large scale, multiple independent controllers will be needed to cover the IoT demands where each group of devices will report to one controller. Each controller is associated with multiple edge servers from the other side which ensures enough resources to serve the devices’ requests. The IoT devices initially send their requests including tasks to be processed to the edge using the available network resources. The efficient allocation of network resources to connect the edge to the IoT devices is out of the scope of the paper. Once the IoT state including the resource demand is received by the controller, the controller will run EDRL scheme to find the most appropriate resource allocation action that maximize the device’s gain. Thus, all the EDRL related interactions occur at the edge which is assumed to have enough resources to handle such overhead.

The budget assigned to the IoT device is denoted as \(B\). It is exploited to obtain the necessary resources and is determined according to the device’s BRDI calculated in Section 4.2. The resource requests initiated by the IoT devices are assumed to be independent and each request aims for certain resource ratio from certain edge server. This amount of resources is called resource demand. For instance, if an IoT device requires 5 units of CPU and 3 units of memory, the resource demand will be defined as \((CPU : 5, MEM : 3)\). The number of successfully served requests depends on the amount of resources allocated for it. For example, if the IoT device acquires 8 units of CPU and 6 of memory, these resources will be sufficient to serve 2 requests as \(\min(\frac{2}{5}, \frac{2}{3})\). The set of edge servers, the set of IoT devices, and the set of \(K\) different resource types are denoted by \(J\), \(N\), and \(K\) respectively. Let \(i, j, k\) be the indexes of IoT device, edge server, and resource type. Then, the demand vector of device \(i\) is defined as \(X_i = (x_{i,1}, x_{i,2}, ..., x_{i,K})\), where \(x_{i,k}\) is the amount of resources of type \(k\) requested by IoT device \(i\). Similarly, the amount of resources of type \(k\) that is allocated to device \(i\) from edge server \(j\) is denoted by \(y_{i,j,k}\) and the allocation vector of all resources from edge server \(j\) is \(Y_{i,j} = (y_{i,j,1}, y_{i,j,2}, ..., y_{i,j,K})\). The capacity of the available resources of type \(k\) at the edge server \(j\) is denoted by \(CP_{j,k}\). The resource allocation vector is represented by a matrix in which the row presents the resources allocated and the column is the type of resources. We evaluate the gain of each IoT device using
RFTA Gain Function denoted by $G_{R}^{i} : K^{I \times K} \rightarrow K$ which maps each resource allocated to a number quantifying the device satisfaction given the resource allocated. It is found with respect to the number of successfully served requests $Z_{i}(Y_{i})$ for IoT device $i$ with $Y_{i}$ as the resources allocated. Thus, the gain is given as,

$$G_{R}^{i}(Y_{i}) = Z_{i}(Y_{i}) = \sum_{j} Z_{i,j}(Y_{i,j}) = \sum_{j} \min_{k} \frac{y_{i,j,k}}{x_{i,j,k}} \quad \forall i \quad (4)$$

The demand vector $X_{i}$ is assumed to be finite. Basically, maximizing the gain will maximize the satisfaction of IoT devices (number of successfully served requests) given the resources of different types allocated and limited by the devices’ budgets.

The gain defined in (4) is proportional to the budget $B_{i}$ assigned to the IoT device $i$. To determine the budget $B_{i}$, we consider three main factors: 1) the BRDI of IoT device $i$ obtained from Section 4.2; 2) the ultimate budget that should be awarded to a normal device $i$ with BRDI equals 1; and 3) the priority of the application running on the IoT device $\xi_{i}$. For example, the IoT applications that require real-time response are given higher priority as in Fig. 1. The ultimate budget $B_{U}$ is modeled as the time required by the IoT device to access certain edge resource ($T_{s}$). It is determined based on the amount of data $DA$ that the IoT device needs to process, the number of necessary processing units of certain resource $U_{k}$, and $\tau$ which is the processing factor determined according to the resource type $k$. Thus, the ultimate budget for each IoT device is given as $B_{U} = \xi_{i} \sum_{k} T_{s} = \xi_{i} \sum_{k} \frac{DA}{\tau U_{k}}$. The budget $B_{i}$ is given as,

$$B_{i} = \Gamma_{i} B_{U} \quad (5)$$

where $\Gamma_{i}$ is the BRDI of IoT device $i$.

### 5.2 Problem Formulation

In this subsection, we formulate the resource allocation problem such that IoT device $i$ uses its assigned budget $B_{i}$ to acquire resources from edge servers. The cost of resources provided from edge server $j$ is defined as $c_{j} = (c_{j,1}, c_{j,2}, ..., c_{j,K})$, each element $c_{j,k}$ represents the cost of resources of type $k$ from edge server $j$. The resource allocation for device $i$ is formulated as an optimization problem with objective of maximizing the gain $G_{R}^{i}$ as follows,

$$\max_{Y_{i,j}} G_{R}^{i} = \sum_{j} Z_{i,j}(Y_{i,j}) \forall i \in N \quad \text{s.t.} \quad \begin{align*}
C.1 & \quad \sum_{j} \sum_{k} y_{i,j,k} c_{j,k} \leq B_{i}, \\
C.2 & \quad \sum_{j} \sum_{k} y_{i,j,k} \leq C_{P,j,k} \forall j, k, \\
C.3 & \quad y_{i,j,k} \geq 0 \quad \forall j, k, \quad C.A \quad c_{j,k} \geq 0 \quad \forall j, k
\end{align*} \quad (6)$$

The constraint C.1 in (7) confirms that the amount of resources to be allocated to IoT device $i$ is controlled by its assigned budget. This fulfills the objective of adapting resource allocation based on the BRD of the IoT device. The constraint C.2 ensures that the allocated resources from certain edge server $j$ do not exceed the server $j$ capacity. In addition, the allocated resources cannot be 0 as in C.3. The last constraint C.A indicates that the resources cannot be allocated at $c_{j,k} = 0$. This constraint also reveals that those IoT devices with BRDI = 0 are not able to obtain any resources as they will not have budget to cover the cost. Our goal is to find the allocation policy that guarantees maximization of the IoT device’s gain defined in (6).

The optimization problem is formulated based on RFTA model as in Fig. 6. From one side, the budget of the IoT device is determined using its resource demand, the ultimate budget for such demand and the BRDI of the device. RFTA gain is exploited from the other side. The capacity and budget constraints are enforced into the optimization objective which aims to maximize the IoT devices’ gain through efficient resource allocation.

### 5.3 Rationality, Fairness and Truthfulness

The formulated problem in (6) and its associated constraints guarantee rationality, fairness, and support truthfulness as follows. The proposed model guarantees rationality for each IoT device. For example, a device $i$ with $\Gamma_{i} = 0$, will have budget $B_{i} = 0$ and eventually will have $G_{R}^{i} = 0$. On the other hand, a device $l$ with $\Gamma_{l} > 0$, will have $B_{l} > 0$ and $G_{R}^{l} > 0$. This gain is valid since the cost of the allocated resources for the device $l$ is within the confines of its budget. Hence, the proposed resource allocation model is rational as $G_{R}^{i} \geq 0$. We exploit envy-freeness [34] feature to demonstrate that the RFTA model is fair for all IoT devices with consideration of budget variation. Envy-freeness indicates that every device is satisfied with its allocation gain and does not prefer other devices’ allocation. If the budget is the same for all the devices with the same application, all the devices demonstrate envy-freeness if $Z_{i}(Y_{i}) = Z_{l}(Y_{l})$, where $i \neq l$. However, since the budget in our model varies, we modified the typical definition of envy-freeness such that the allocation is envy-free if,

$$Z_{i}(Y_{i}) \geq Z_{i}(\frac{B_{i}}{B_{q}} Y_{q}) \forall i, q \in N \quad (10)$$

This is demonstrated as follows. Equation (10) can be written as,

$$B_{q} Z_{i}(Y_{i}) \geq B_{i} Z_{i}(Y_{q}) \forall i, q \in N \quad (11)$$

Let $C_{i,j,k}$ be the total cost of the resources allocated with type $k$ from edge server $j$ to device $i$. According to (4),

$$B_{q} Z_{i}(Y_{i}) = B_{q} \sum_{j} \frac{y_{i,j,k}}{x_{i,k}} = B_{q} \sum_{j} \frac{C_{i,j,k}}{x_{i,k}} \quad (12)$$
if \( \psi_i \geq \frac{1}{x_i,k,c_{j,k}} \)

\[
B_q \sum_j C_{i,j,k} = B_q \sum_j C_{i,j,k} \tag{13}
\]

\[
B_q \psi_i \sum_j C_{i,j,k} = B_q \psi_i \sum_j C_{i,j,k} \tag{14}
\]

\[
\psi_i B_i \sum_j C_{q,j,k} \geq B_i \sum_j C_{q,j,k} = B_i \sum_j y_{q,j,k} \tag{15}
\]

\[
B_i \sum_j y_{q,j,k} = B_i Z_i(Y_q) \tag{16}
\]

Thus, the envy-freeness condition in (10) is satisfied.

To justify truthfulness in RFTA model, we consider two scenarios on how IoT devices report their resource demands. In the first scenario, the IoT devices report unusual demands for resources because of their malfunction. The minimal budget assigned and consequently the limited resource allocation will alarm the IoT users that there is a malfunction in these devices. They will only receive their fair share of resources if they truthfully report their resource demand. The second scenario is caused by the cheating IoT devices which intentionally report fraudulent resource demand. These devices will be penalized by receiving low/zero budget which makes them unable to afford the available resources. In both scenarios, IoT devices will have: \( \Gamma < 1, B < B_0 \), and \( G_R \neq \max \). As a result, this guarantees that malfunctioned IoT devices will be fixed and become truthful in reporting resource demands and the abnormal devices will be encouraged to be truthful to achieve resource allocation with maximum gain.

### 6 Enhanced Deep Reinforcement Learning for Edge Resource Allocation

In this section, we develop an enhanced deep reinforcement learning (EDRL) scheme for Edge-IoT resource allocation that follows MDP with RFTA gain defined in Section 5 as the optimization objective.

#### 6.1 MDP Formulation

In this subsection, we formulate an MDP to maximize the RFTA gain of IoT devices defined in equation (6). The developed MDP consists of the following components:

**State:** The state is observed with each resource request arrival at epoch \( t \). The state in our developed MDP is composite and includes partial state and comprehensive state elements. The partial state is defined as \( s_{j,t} = CP_j(y) \), where \( CP_j(y) \) is the available resource vector defined as \( CP_j(y) = \{y_{i,j,1}, y_{i,j,2}, \ldots, y_{i,j,k}\} \) at edge server \( j \). Each element in this vector corresponds to the resources available of type \( k \) at server \( j \). The comprehensive state \( s_t \) is the combination of the resource availability information for all edge servers and the device state information including budget and resource demand. It is defined as \( s_t = (CP(y), X_t, B_t) \), where \( \{CP(y)\}_{j=1}^{j=J} \) represents the aggregation of the available resource vectors \( CP_j(y) \). \( X_i \) is the vector of resource demand which triggers the MDP and \( B_t \) is the device’s budget.

**Action:** The action is performed when a comprehensive state transition occurs due to resource request. The action is defined as \( a_t = (Y_{i,j} = \{y_{i,j,1}, y_{i,j,2}, \ldots, y_{i,j,k}\}) \) where \( Y_{i,j} \) is the vector of the resource of type \( k \) allocated to device \( i \) and provided by edge server \( j \). The allocation action depends on not only the IoT device state, but also the edge servers state such that if \( CP_j(y) \) is saturated or the allocation cost exceeds the device’s budget, allocation does not occur. Thus, the action space is defined as:

\[
A_s = \begin{cases} 
\{0\}, & Y_{i,j} > CP_j(y), \text{or} \sum_j \sum_k y_{i,j,k} c_{j,k} > B_t \cr 
\{1\}, & Y_{i,j} \leq CP_j(y), \text{and} \sum_j \sum_k y_{i,j,k} c_{j,k} \leq B_t \end{cases} \tag{17}
\]

**Transition Probability:** Given the state \( s_t \) and the action \( a_t \), the transition to the state \( s_{t+1} \) occurs as \( s_t \rightarrow s_{t+1} \) in two steps. The first step determines the after-action state which is given as \( s'_{t+1} = f(s_t, a_t) = (CP'_j(y), X_t, B'_t) \). \( CP'_j(y) \) and \( B'_t \) indicate the capacity of edge server \( j \) and the budget of IoT device \( i \) respectively, are updated to reflect the resource allocation action. The second step specifies the state at \( t+1 \) and is defined as \( s_{t+1} = f(s'_t, X^{t+1}_t) \). Note that the device’s demand \( X^{t+1}_t \) is valid if there is a new resource request from device \( i \) at \( t+1 \). The transition probability is found as \( T_R(s_{t+1}|s'_t) = \lambda_t/\beta(s'_t) \), where \( \lambda_t \) is the average arrival rate of resource requests from device \( i \) and \( \beta(s'_t) \) is a parameter of exponential distribution to find the duration of \( t \) which is the time duration of the MDP in state \( s_t \) given the action \( a_t \). It is evaluated according to the arrival rate of resource requests and the time given to access the allocated resources.

**Reward Function:** The reward function aims to fulfill the optimization objective defined in (6) in the RFTA model. The EDRL allocation policy \( \pi \) is found such that the gain of IoT devices is maximized. The policy \( \pi \) is a function that determines the action \( a_t = \pi(s_t) \) that the scheme selects in state \( s_t \). The reward function \( R(s_t, \pi(s_t)) \) is derived to account for the impact of \( \beta(s_t) \) according to the theory in [35] as \( R(s_t, \pi(s_t)) = \rho(s_t, \pi(s_t))/\beta(s_t) \), where \( \rho(s_t, \pi(s_t)) \) is found based on the number of served requests \( Z_i(Y_t) \) defined in (4) and \( R(s_t, a_t) = R'(s'_t) \) is expressed as a function of after-action state \( s'_t \). The optimal resource allocation policy of the MDP model is achieved according to after-action bellman equation as:

\[
V(s'_t) = \sum_{s_{t+1} \in S} T_R(s_{t+1}|s'_t) \max_{\pi} \left( R'(s'_{t+1}) + \frac{\theta}{\beta'(s'_{t+1})} \right) \tag{18}
\]

\( V(.) \) is the after-action comprehensive value function and \( \theta \) is the reward rate.

#### 6.2 Value Function Approximation

In this subsection, we illustrate the proposed novel approximation of the EDRL value function. To formulate the value function approximation, we introduce a mapping function between the comprehensive state and the partial state after the action is selected. We denote
$s^{(m)} \in S$ as the after-action comprehensive state in its state space. $n = m(j)$ represents the index of the after-action partial state within its state space when the comprehensive state is $s^{(m)}$. Thus, we can claim that $s^{(m)} = \{s^{(m(j))}\}_{j=1}^J$. The value function in (18) is approximated as follows,

$$V(s^{(m)}) = \sum_{j=1}^J \sum_{n=1}^n \phi_{s_j^{(n)}}(s^{(m)}) V_j(s_j^{(n)}) \tag{19}$$

where $\Omega = |S_j|$ is the cardinality of the state space of edge server $j$ and $V_j(s_j^{(n)})$ is the value function for allocation of resources from edge server $j$ for its after-action partial state $s_j^{(n)}$. The feature vector for the after-action comprehensive state is defined as $\phi_{s_j^{(n)}}(s^{(m)}) = 1$ if $n = m(j)$ and all features of the after-action partial state $s_j^{(n)}$ are the same for all the comprehensive states that $s_j^{(n)}$ belongs to, that is,

$$\{\phi_{s_j^{(n)}}(s^{(m)})\}_{m \in |S_j|, n = m(j)} \tag{20}$$

So far, the approximation in (19) is inaccurate. Hence, we use DNN to train the values $\phi_{s_j^{(n)}}(s^{(m)})$ and $V_j(s_j^{(n)})$.

The approximation in (19) can be re-written as,

$$V(s^{(m)}) = \mathbf{V}\phi(s^{(m)}) \tag{21}$$

where $\mathbf{V}$ is the $(J \times \Omega)$-dimensional value function vector with $(j-1)\Omega + n$th element as $V_j(s_j^{(n)})$. The value function in (18) is updated with the approximation in (19) as follows,

$$\sum_{j=1}^J \phi_{s_j^{(n)}}(s_j^{(n)}) V_j(s_j^{(n)}) = \sum_{s_{t+1} \in S} T_R(s_{t+1}|s_t) \max_{\pi} \left( R'(s_{t+1}) + \sum_{j=1}^J \phi_{s_j^{(n)}}(s_j^{(n)}) V_j(s_j^{(n)}) - \frac{\theta}{\beta(s_{t+1})} \right) \tag{22}$$

The action $s'_t$ is selected according to the policy $\pi^*(s_t)$ with objective of maximizing (22) as follows,

$$\pi^*(s_t) = \max_{\pi} \left( R'(s_t') + \sum_{j=1}^J \phi_{s_j^{(n)}}(s_j^{(n)}) V_j(s_j^{(n)}) - \frac{\theta}{\beta(s'_t)} \right) \tag{23}$$

The action space $A_{s_t}$ is created and populated by the resource allocation actions $a_t = (Y_{t,j})$. To derive the value function vector, DNN layers’ weights, and the reward rate mentioned before, we exploit stochastic gradient method under function approximation [15]. Thus, the loss function is defined as,

$$L_t(\mathbf{V}_t, w_t^\pi, w_t) = \frac{1}{2} E \left( \max_{\pi} \left( R'(s_t') + \sum_{j=1}^J \phi_{s_j^{(n)}}(s_j^{(n)}) V_j(s_j^{(n)}) - \frac{\theta}{\beta(s_t)} \right)^2 \right) \tag{24}$$

where $\theta_t$ is the reward rate up to epoch $t$. The gradient of the loss function is found using back-propagation DNN.

The MDP model integrated with EDRL is presented in Fig. 7. The figure shows that the state information of the IoT devices and the comprehensive state of all edge servers are exploited by the EDRL to select the most appropriate resource allocation action. DNN is used to tackle the dimensionality problem in RL through the proposed novel approximation of DRL value function.

![Fig. 7. MDP based EDRL scheme](image)

The inference complexity of the proposed DRL scheme executed over $T$ allocation intervals is $O(TM \log \omega + TNY\omega)$, where $N$ and $M$ are the number of edge servers associated with the controller and the total number of IoT devices respectively, $\omega$ is the number of IoT devices requested resources at the current interval, and $Y = \sum_{j,k} Y_{t,j,k}$ denotes the available resources at the edge servers; where $j$ and $k$ are the indexes for the edge server and resource type respectively. Note that the inference complexity per allocation interval increases linearly with the number of edge servers and IoT devices.

### 7 PERFORMANCE EVALUATION

We evaluate the performance of BEHAVE in terms of the detection accuracy of the irregular BRD, detection overhead, IoT devices’ gain, fairness, variance of edge server load and convergence. The evaluation studies the impact of different settings on the achieved IoT devices’ gain including the number of IoT devices, the application type, the number of edge servers, and the budgets of IoT devices.

#### 7.1 Evaluation Setup

In the following evaluation, we simulate an Edge-IoT environment that includes 500 IoT devices and 100 edge servers with three types of resources: CPU, memory and bandwidth. These numbers are used in all the simulation unless otherwise indicated. We consider four types of IoT applications with various requirements from Fig. 1: emergency response, home voice assistant, building access face detection and health monitoring. The number of IoT devices deployed in this simulation is variable with ratio of 1/4 for each application. The resource demand (request) for each IoT device is determined according to its application. They are generated following Poisson distribution in the following ranges $[0.1, 0.8]$ for vCPU, $[0.8, 4]$ GB for memory and $[10, 60]$ Mbps for bandwidth. We normalize the resource capacity of edge servers. Thus, the resource capacity of each edge server is of one unit ($CP_{j,k} = 1 \forall j, k$). The computing capacity of the edge servers is set between 1 GHz and 5 GHz. The average data transmission rate is distributed between 250 Mbps and 1000 Mbps. It is assumed that the budget
for each IoT device is determined according to its BRDI. The budget is normalized to have value between 0 and 1. For example, the healthy IoT device will have budget equals 1 (i.e. it will have access time to edge resources that fully satisfies its demands). The resource access time at the edge servers is modeled with consideration of the following factors: edge server available resource \( E_{R_{j,k}} \) of type \( k \) such as CPU frequency, and the IoT resource demand \( X_{i,j} \). The access time for resource \( k \) at server \( j \) is found as \( T_s = \frac{X_{i,j}}{E_{R_{j,k}} y_{i,j,k}} \), where \( y_{i,j,k} \) is the amount of resource of type \( k \) allocated to device \( i \) from server \( j \). Note that \( E_{R_{j,k}} \) varies considering different edge servers. Machine learning algorithms are executed using double Intel i7 quad core 3.4 GHz CPUs, 16 GB Random Access Memory (RAM), and 512 GB disk. The edge servers are chosen from the set of M4 Amazon EC2 instances [36]. Amazon M4 instance of type M4.10xLarge includes 40 vCPU, 160 GiB of memory, and 4 GHz of bandwidth. To evaluate the performance of \( BEHAVE \) with respect to resource allocation, we consider the DQN scheme proposed in [19], DRLRA scheme in [20], and the optimal exhaustive search for comparison.

Fig. 8 shows the optimal search for comparison. First Step (Modeling and assessment of IoT devices’ BRD): The BRD manager in \( BEHAVE \) learns the normal BRD patterns. When the IoT device initiates resource request to the edge, the BRD manager dynamically synthesizes the device demands and generates its corresponding BRD. The BRDI is updated based on current and history status of the device.

Second Step (Device’s Budget Determination): This step determines the budget to be assigned to each IoT device according to the following: 1) BRDI value determined at the first step; and 2) Device priority determined based on the application type. For example, a device running emergency response application will be given higher budget than a health monitoring device provided that they have the same BRDI since the emergency response application has the higher priority.

Third Step (Resource Allocation): This step allocates the required resources for heterogeneous devices with certain cost according to their assigned budget and the resources availability at the edge. This is achieved through the adopted MDP model and EDRL scheme with IoT devices’ gain as the optimization objective. Various evaluations detailed in the next subsections are conducted to demonstrate \( BEHAVE \) capabilities.

7.2 Irregular BRD Detection

7.2.1 Detection Performance

We implement a real Edge-IoT testbed running three typical IoT applications: building access face detection (BAFD), home voice assistant (HVA) and health monitoring (HM). These applications represent video, audio, and sensor data processing tasks on the edge nodes respectively. Thus, their behaviors are typical examples to show the modeling ability and assessment accuracy of our proposed scheme. The testbed includes edge server with 2.7 GHz CPU and 8 GB memory, and three Raspberry Pi 3 Model Bs to implement the three applications. For BAFD, the Raspberry Pi is integrated with a Pi Camera Module v2. An USB microphone is connected to the Raspberry Pi to implement HVA. We utilize a Pi sensorhat to deploy HM application. Open-source OpenCV [37], Natural Language Tool Kit [38], and Sense HAT python-based library [39] are exploited as the software platforms to process edge computing requests. Table 1 presents the hardware and software platforms employed for each application.

TABLE 1

<table>
<thead>
<tr>
<th>Application</th>
<th>Hardware</th>
<th>Software</th>
</tr>
</thead>
<tbody>
<tr>
<td>Building access face detec-</td>
<td>Pi Camera</td>
<td>Open-source</td>
</tr>
<tr>
<td>tion (BAFD)</td>
<td></td>
<td>OpenCV</td>
</tr>
<tr>
<td>Home voice assistant (HVA)</td>
<td>USB microphone</td>
<td>Natural Language</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Tool Kit</td>
</tr>
<tr>
<td>Health monitoring (HM)</td>
<td>Pi sensorhat</td>
<td>Sense HAT</td>
</tr>
</tbody>
</table>

To generate the irregular BRD for SR behavior granularity, we create the edge resource overuse by inserting the large sized tasks in normal traffic of a random request or occupying connection for a longer time. For the TR granularity, we send more service requests in certain time slot. In order to evaluate the performance, F1 score [40] is adopted to compute the detection accuracy considering both the precision and recall values. The F1 scores from the two granularities are tested separately, in which 10 repeated experiments are made and average scores are calculated.

For the SR, we compare OCNN model in \( BEHAVE \) to other three state-of-the-art OCC detection methods, including Robust Co-variance (RC) [41], Isolation Forest (IF) [42], and OC-SVM [32]. Fig. 9 shows that \( BEHAVE \) outperforms the other models for all the three applications. For the TR, we compare GAN-ED+OCNN model in \( BEHAVE \) to other two popular detection methods, Autoencoder (AE) [28] and integration of Autoencoder and OC-SVM (AE+OC-SVM) [43]. Fig. 10 shows that the proposed GAN-ED+OCNN achieves better detection accuracy than the other models. We also notice that...
HM has significant accuracy variation using AE and AE+OC+SVM models. The reason is that HM has relatively more static behavior than BAFD and HVA. The feature learning ability of GAN-ED for time-series BRD is a key contributor to the performance.

\[ MTT (s) \quad BDT (ms) \quad MRM (MB) \]

9 - 11 s 18 - 20 s 65 - 95 ms 163 - 184 MB 190 - 230 ms 63 - 89 MB

**TR Detection Accuracy**

<table>
<thead>
<tr>
<th>Model</th>
<th>MTT (s)</th>
<th>BDT (ms)</th>
<th>MRM (MB)</th>
</tr>
</thead>
<tbody>
<tr>
<td>GAN-ED</td>
<td>18 - 20 s</td>
<td>190 - 230 ms</td>
<td>163 - 184 MB</td>
</tr>
<tr>
<td>OCNN</td>
<td>9 - 11 s</td>
<td>63 - 95 ms</td>
<td>63 - 89 MB</td>
</tr>
</tbody>
</table>

**7.3 IoT Devices Gain**

The achieved gain value maps the resources allocated to a number that quantifies the IoT satisfaction given the resources allocated \( G^i_K (Y_i) : K^{M \times K} \rightarrow K \), where \( K \) is the resource index defined in the system model. In the following, we study the impact of the number of IoT devices, the number of edge servers, and the edge servers processing capacities on the achieved gain of the IoT devices. Fig. 11(a) shows the gain of all IoT devices vs. the number of edge servers. The figure indicates that the gain increases as there are more edge servers available to provide more resources that satisfy the demand of IoT devices. To study the impact of the number of IoT devices on the achieved gain which mainly impacts the demand for resources from the edge, we evaluate the performance for 125 devices that run the emergency response application. Fig. 11(b) presents the achieved gain for each IoT device vs the number of IoT devices. It is definite that the increase in the number of IoT devices leads to a decline in the achieved gain as the demand increases and competition for resources between IoT devices escalates. BEHAVE maintains the gain at reasonable level when the number of IoT devices is large. Fig. 11(c) presents the IoT devices’ gain as a function of the processing capacity of edge servers. It is observable from Fig. 11(c) that as the computing power of edge servers increases, the devices’ gain gradually improves. Thus, the number of satisfied resources requests increases. It is also obvious that when the computing capability of the edge server is moderate, a performance gap exists between BEHAVE and other schemes. We clearly notice that BEHAVE outperforms other DRL based resource allocation schemes in the IoT devices’ gain evaluation specifically at critical system settings such as small number of edge servers and large number of IoT devices. In addition, we notice that BEHAVE achieves IoT gain close to the optimal exhaustive search based scheme that is within the range of 1%. Exhaustive search requires searching through all the possible resource allocation possibilities. It is impractical in the considered edge-IoT system given the fact that the search becomes complicated and consumes significant time as the network scale grows in terms of the numbers of IoT devices, edge server and edge resources.

**7.4 Fairness and Budget Impact**

In this evaluation, we demonstrate BEHAVE capability to maintain fairness among different IoT devices in resource allocation. In addition, we explore the impact
We selected a group of 8 IoT devices where each 2 devices run one of the applications stated in the evaluation setup. IoT devices, their applications and the BRD indexes are given in Table 3. We notice that device D which runs emergency response application and records the highest BRDI of 0.98, achieved the highest budget. The gain for each IoT device is presented in Fig. 13. This evaluation clearly demonstrates the budget impact on the gain achieved. In addition, it shows that BEHAVE is effective in capturing the application priority in resource allocation as even if two devices have the same BRDI but with different applications, they achieve different gain.

### 7.5 Resource Allocation Balancing

In this evaluation, we focus on the impact of the number of IoT devices and processing capacity of edge servers on the balance of resource allocation over the edge servers. Fig. 14 shows that as the number of IoT devices grows, the variance of edge servers load increases since the number of resource requests increases at each edge server. Moreover, Fig. 14 presents the normalized mean of the servers load vs. the number of IoT devices. The normalized mean of the servers’ load is defined as the ratio between the load of IoT tasks and the capacity of the edge servers and takes a value between 0 and 1. It is noticed that while all the schemes have the same mean of servers load, the variance is different. The mean of servers’ load is identical for all schemes as amount of tasks requested to be processed by certain IoT devices is the same and the variance value varies as the amount of the tasks assigned to each edge server (i.e. how much is the load for each edge server) is different. BEHAVE is very effective in balancing the load on edge servers as shown in Fig. 14 as it makes the variance more stable than other schemes. It is also evident that the merit of BEHAVE is clear over other schemes when the number of devices increases. Fig. 15 indicates that with increasing of processing capacity of edge servers, the server load variance and the computation load become more manageable and balanced. We also notice in Fig. 15 that as the processing power increases, BEHAVE outperforms other schemes.

![Fig. 11. IoT gain Evaluation](image)

![Fig. 12. EF index with variable number of edge servers](image)

![Fig. 13. IoT gain with variable devices budgets](image)

![Fig. 14. Variance and mean of edge server load](image)
exploits a sophisticated deep neural network to approximate value function in DRL. Evaluation results demonstrate BEHAVE’s capabilities including detection of devices’ irregular BRD, optimizing devices’ gain, and maintaining fairness.

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Fig. 15. Variance of edge server load vs edge servers’ capacity

7.6 BEHAVE Convergence

We conduct this evaluation to demonstrate the convergence performance of BEHAVE. Fig. 16 shows the achieved gain of the IoT devices against the number of epoch. We notice that at the beginning, the gain is low because DRL agent does not have enough experience to make rational decisions for resource allocation. With the increase in the number of epoch, the gain increases gradually until a relatively stable value is reached. Fig. 16 also shows that BEHAVE converges faster than other DRL based schemes.

All the evaluations reveal the advantages of BEHAVE design principles including: 1) IoT devices’ BRD modeling and assessment in two granularities using novel deep learning scheme; 2) resource allocation model that is characterized as rational, fair and truthful; 3) the enhanced MDP model that collects full state information including: device budget, resource requests and resource availability at all edge servers; and 4) EDRL scheme with novel accurate value function approximation for solving dimensionality problem of DRL.

8 CONCLUSION

The paper has tackled the resource allocation problem in Edge-IoT environment with consideration of the IoT devices’ BRD. We proposed BEHAVE framework which comprises BRD modeling and assessment mechanisms, novel RFTA model and EDRL scheme. The modeling of BRD mechanism exploits deep learning to assess the IoT devices’ BRD. RFTA model assigns budgets to IoT devices according to their practiced behavior. These budgets are used to obtain resources from the edge that satisfies the IoT devices’ demands. RFTA model achieves rational and fair resource allocation policy that encourages IoT devices to be truthful in reporting their resource demands. BEHAVE employs an EDRL scheme which learns by reinforcement resource allocation policy that maximizes the devices’ gain. Moreover, BEHAVE